



Gerry Chen

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OVERVIEW

Interested in robotics dynamics and control. Georgia Tech Robotics PhD cohort of 2019.

EDUCATION

Georgia Institute of Technology <i>College of Computing</i> PhD Robotics under Professor Frank Dellaert	08/2019 to Present
Duke University <i>Pratt School of Engineering</i> BSE Electrical & Computer Engineering, BSE Mechanical Engineering, CS (minor), Math (minor) 3.87/4.00 cumulative GPA, Magna Cum Laude	08/2015 to 05/2019

PUBLICATIONS

3. P. Grady, [G. Chen](#), S. Verma, A. Marellapudi, N. Hotz, “[A Study of Energy Losses in the World’s Most Fuel-Efficient Vehicle](#)”, *IEEE Vehicle Power and Propulsion Conference (VPPC)*. (2019).
2. Z. Li, A. Yang, [G. Chen](#), Z. Zeng, A. Peterchev, S. Goetz, “[A Modular Multilevel Pulsating DC-Link Inverter for Electric Vehicle Drives with Increased Efficiency](#)”, *IEEE Transactions on Transportation Electrification (TTE)*. **In Review** (2019).
1. F. Wang, [G. Chen](#), and K. Hauser, “[Robot Button Pressing in Human Environments](#)”, *2018 IEEE International Conference on Robotics and Automation (ICRA)*. p 7173-7180 (2018).

RESEARCH EXPERIENCE

Robotic Kinodynamics <i>Georgia Institute of Technology - Dr. Frank Dellaert</i> <ul style="list-style-type: none">• Design and control of a cable driven parallel robot for painting graffiti• Factor graphs (GTSAM) for MPC	08/2019 to Present
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Power Electronics

08/2018 to 05/2019

Duke University - Dr. Stefan Goetz and Dr. Angel Peterchev

- Implementing novel FOC motor controller using modular multilevel series-parallel converter to self-balance battery cells, reduce noise, increase voltage ratings, and minimize losses
- Thermal analysis of battery/converter modules for use in automotive setting
- Electrical losses analysis for MOSFET selection in converter modules
- Installation of novel motor controller in electric vehicle to test practical cell-balancing performance

Fuel Cell Hybrid Vehicle

08/2017 to 05/2018

Duke University - Dr. Josiah Knight and Dr. Nico Hotz

- Optimization of fuel cell operating parameters for use in hybrid vehicle to achieve 58.9% in-system efficiency (increase from baseline efficiency of 40%)
- Design and optimization of voltage converter for active supercapacitor load power leveling system resulting in 22% higher vehicle efficiency
- Writing papers for fuel cell optimization, hybrid system integration, and vehicle system level design

Robotics Motion Planning

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Applied convolution-based image similarity metrics for database assisted vehicle path planning
- Fabricated silicon and polyurethane cornea models with <50um repeatability for use in surgical robot testing
- Submitted joint paper to IEEE International Conference on Robotics and Automation 2018 (Accepted 01/12/2018) - work funded by NSF Research Experiences for Undergraduates (REU) to implement a Precision Positioning Unit (PPU) on the Tele-Robotic Intelligent Nursing Assistant (TRINA)
- Redundancy resolution for minimum manipulability / maximum continuous range joint configurations
- Fabricated polyurethane “finger” tip with integrated tactile sensor and 95.7% actuation success rate

EXTRACURRICULAR ACTIVITIES

Co-President

08/2015 to 08/2019

Duke Electric Vehicles Team

- World Record (2019): World’s most efficient electric vehicle - team president
- World Record (2018): World’s most fuel efficient vehicle - head of hydrogen system
- Lead creation of a fully autonomous vehicle to allow the vehicle to follow a “total system energy” optimized path subject to physical control constraints
- Co-lead hydrogen fuel cell hybrid vehicle for 2018 to achieve 14,573 MPGe
- Design + Manufacture + Test the high power super-capacitor control board to increase vehicle efficiency by 22%
- Create an automated testing system resulting in fuel cell efficiency increase from 40% to 63%
- Design + Manufacture + Install the carbon fiber inserts to decrease weight and increase modularity
- 2018: 1st place H2, 1st place battery-electric (12,398 MPGe), Technical Innovation Award at the Shell Eco-Marathon Americas

CTO

08/2018 to 05/2019

Delta Band Inc. - deltatrainer.fit

- Designed all electrical systems of the strength training workout tracker watch based on machine learning
- Currently on 7th generation electrical boards (Dec 2018)
- Initiating small-scale (100 devices) manufacturing for beta-testing devices to be shipped Jan 2019

Project Lead

01/2016 to 01/2018

Solar Benches

- Lead technical, financial, and administrative aspects of augmenting existing campus benches with solar powered night-time task lighting and laptop/phone chargers to raise enthusiasm for clean energy
- Installed 2 test benches on campus after passing safety inspection on an off-site prototype bench

WORK HISTORY

Integrated Control and Estimation Intern

06/2020 to Present

Air Force Research Laboratory (Eglin AFB) - Dr. Adam Rutkowski

- Refine collaborative vehicle control with imperfect multi-vehicle trajectory estimations
- Compute optimal sensor measurement timing and inter-vehicle communication
- Compute optimal collaborative trajectories to minimize navigation uncertainty using factor graphs

Controls Engineer Intern

05/2018 to 08/2018

Deka R&D - Dirk Van Der Merwe

- Developed novel 2-wheel balancing control scheme with constrained wheel displacement (patent pending)
- Created multi-system integration over CAN, EtherCAT, RS232 to create hybrid wheeled/legged robot
- Developed stability control of robot w/ powered casters + differential steering to test high speed dynamics

Robotics Motion Planning Intern

01/2017 to 05/2018

Intelligent Motion Laboratory - Dr. Kris Hauser

- Work on PPU for TRINA (see entry in Research Experience)
- Coded (Python, C++) and tested max. continuous range / min. manipulatability arm configurations

Teaching Assistant

08/2019 to Present

Georgia Institute of Technology

- **CS3630:** Intro Perception & Robotics Fall 2019

Teaching Assistant

08/2016 to 05/2018

Duke University

- **EGR201:** Mechanics of Statics Fall 2017
- **ECE230:** Microelectronics Fall 2017
- **ECE230:** Microelectronics Summer 2017
- **EGR103:** Computational Methods in engineering Fall 2016
- **CS201:** Data structures and Algorithms Fall 2016

Tutor

05/2014 to 05/2019

Multiple Employers

- Duke Academic Resource Center - group instruction:
 - Multivariable Calculus 08/2016 to 05/2019
 - Linear Algebra 01/2017 to 01/2018
 - Differential Equations 01/2017 to 01/2018
- Duke Academic Resource Center - individual instruction:
 - Multivariable Calculus 08/2016 to 05/2017
 - Linear Algebra 08/2016 to 05/2017
 - Differential Equations 08/2016 to 05/2017
- America Reads America Counts at Duke 08/2015 to 06/2016
 - Durham Public Schools
 - Math + Reading
- Kumon Math and Reading Center of Fox Chapel 05/2014 to 08/2016
 - personalized curriculum generation for 40+ students
 - student performance evaluations

RELEVANT COURSEWORK

- CS520/MATH565 - Numerical Analysis
- ME524 - Finite Element Method
- MATH577 - Mathematical Modeling
- MATH216 - Linear Algebra and Diff. Equations
- MATH353 - Ordinary and Partial Diff. Equations
- ECE382/ME344 - Control Systems
- ECE350 - Digital Systems
- ECE280 - Intro to Signals and Systems

SKILLS

- Fluency in Matlab, Python, and C++
- Proficiency in ROS, Java, MATHEMATICA, L^AT_EX
- Embedded Development (MCU, FPGA, Jetson)
- Path Planning + Classical Controls
- Eagle, SPICE, Solidworks, Autodesk Fusion
- Experimental design and sensor data acquisition